L Number	Hits	Search Text	DB	Time stamp
7	97	(382/153).CCLS.	USPAT;	2003/07/02 17:24
			US-PGPUB	
8	174	(382/152).CCLS.	USPAT;	2003/07/02 17:24
			US-PGPUB	1
9	32	((382/152).CCLS.) and robot	USPAT;	2003/07/02 17:26
			US-PGPUB	
10	45	((382/151).CCLS.) and robot	USPAT;	2003/07/02 17:27
1			US-PGPUB	•
11	7	arimatsu-taro.in.	USPAT;	2003/07/02 17:29
			US-PGPUB	
12	130	watanabe-atsushi.in.	USPAT;	2003/07/02 17:29
			US-PGPUB	
14	7	382/141-154;901/47.ccls. and	USPAT;	2003/07/02 17:30
1		watanabe-atsushi.in.	US-PGPUB	1
15	52		USPAT;	2003/07/02 17:34
		or two or several or many) adj (video or	US-PGPUB	
		camera or CCD or image or visual) same		
		(workpiece or work-piece or work adj piece		
		or part or model)		0000/00/00 17 44
16	7	((382/154).CCLS.) and (reference or	USPAT;	2003/07/02 17:44
		register\$3 or registration or teach\$3 or	US-PGPUB	
		train\$3 or learn\$3) with (object or model		
		or part or workpiece or work-piece or work		
		adj piece) same robot	HODAM.	2003/07/02 17:45
18	58	(robot) same (video or camera or CCD or	USPAT; US-PGPUB	2003/07/02 17:45
		image or visual) same (predetermined or	US-PGPUB	
		known or specifi\$2 or determined) near	·	
	27	distance robot same (2-D or two-D or	USPAT;	2003/07/02 17:47
20	21	two-dimension\$2 or "2"-dimension\$2 or	US-PGPUB	2000,0,,02 2
		bi-dimensional or (two or "2") adj	03 10102	
	1	dimension\$2) with distance		
21	15	robot same (reference or register\$3 or	USPAT;	2003/07/02 17:48
21	13	registration or teach\$3 or train\$3 or	US-PGPUB	
		learn\$3) same (video or camera or CCD or	00 1010	
1		image or visual) same (predetermined or		
		known or specifi\$2 or determined) near		
		distance		
19	60	i ·	USPAT;	2003/07/02 17:48
1 - 7		teach\$3 or train\$3 or learn\$3) with (model	US-PGPUB	1
		or part or workpiece or work adj piece)		